

ZEUS 2017 - Lugano, Switzerland  
2017-02-13

## Closed-Loop Control of 3D Printers via Webservices

Felix Baumann and Dieter Roller



# Table of Content

- 1 Motivation and Goals
- 2 Benefits and Drawbacks
- 3 Future Work

Motivation and Goals   Benefits and Drawbacks   Future Work

General

## Author Information

Research group at Univ. of Stuttgart, Germany

Computer aided product development

Additive Manufacturing applications

# Additive Manufacturing/3D Printing

## Additive Manufacturing/3D Printing:

- ▷ Creates physical objects from digital models
- ▷ Layer-wise addition of material
- ▷ Variety of material (e.g., plastics, metals, ceramics)
- ▷ Summarises technologies:
  - Electron Beam Melting (EBM)
  - Fused Deposition Modeling** (FDM, also Fused Filament Fabrication FFF)
  - Laminated Object Manufacturing (LOM)
  - Stereolithography (SLA)
  - Selective Laser Sintering/Melting (SLS/SLM)
  - 3D Printing (3DP)
- ▷ Uses STL (STereoLithography) files, tessellated object description

# Motivation

- ▷ Lacking quality in results
- ▷ Errors and failures during fabrication
- ▷ Material and component wastage
- ▷ Lacking quality control

## Lacking Quality in Results

- ▷ Objects detach
  - ← vibration
  - ← collision
- ▷ Material cut-off
- ▷ approx. 22 mm/s movement speed

Motivation and Goals   Benefits and Drawbacks   Future Work

General

## Proposed System

- ▷ Externalised intelligence (service)
- ▷ Control by service via adaptor
- ▷ Direct machine-code streaming

# Basics – CPS

- ▷ Cyber-physical system = real world object
- + digital representation
- Influencing object via actuator(s)
- ← Acquiring information via sensors



## Benefits

- ▷ Extensible → new 3D printer
- ▷ „Profiles“ (fast, expert user, ...)
- ▷ Shared data (collaboration)
- ▷ No modification of hard- or software
- ▷ Re-manufacturing, non-planar surface
- ▷ Adaptive slicing/manufacturing

## Drawbacks

- ▷ Requires uninterrupted Internet connectivity
- ▷ Low latency
- ▷ Fast roundtrip (within one instruction: 0.14s)
- ▷ False positive (robustness)

# Closed-Loop Control

- ▷ Positional/state data from 3D printer
- ▷ Accurate position data: expensive, requires modification
- ▷ Sensor data: requires analysis and statistical models

# Components

- ▷ 3D printer (requires controllable interface)
- ▷ Service (storage, processing, management)
- ▷ Adaptor (mediator between service and 3D printer)
- ▷ Sensor nodes
- ▷ User (distinction in proficiency)

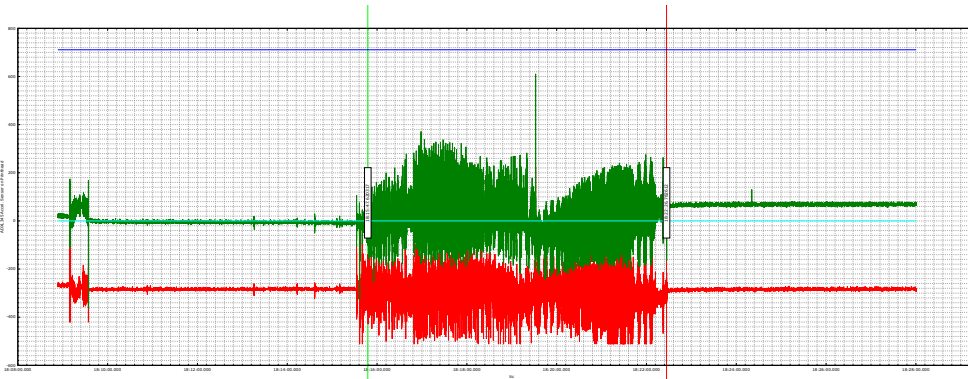
# 3D Printing Model

- ▷ CAD model, STL model, machine code
- vs -
- ▷ (Expected) sensor reading

- 
- ← User input (quality rating)
  - ← Machine learning

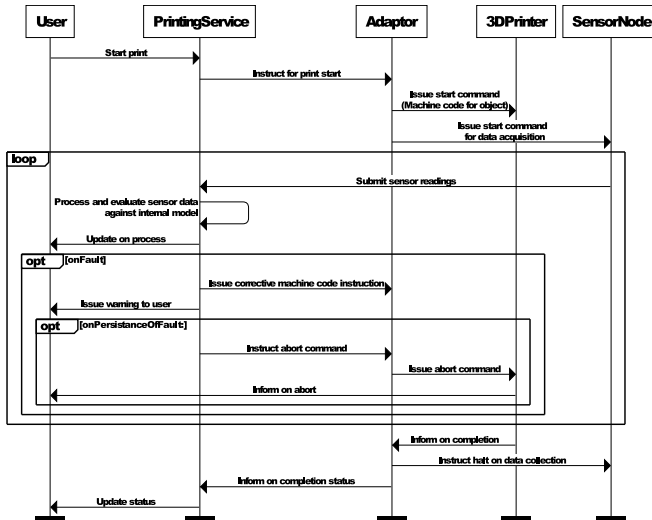
Motivation and Goals   Benefits and Drawbacks   Future Work  
Benefits   Challenges

# Example Sensor Data



Motivation and Goals    Benefits and Drawbacks    Future Work  
 Benefits    Challenges

# Processing Flow



## Challenges

- ▷ Latency in communication
- ▷ Auto-connection (user-friendly)
- ▷ Loss of control for customer



Motivation and Goals   Benefits and Drawbacks   Future Work

Summary

Contact

## Future Work

- ▷ Model creation (requires more data)
- ▷ Testing and evaluation
- ▷ Predictive maintenance

# Summary

- Outline of work-in-progress of 3D printer control with REST
- Motivation
- Architecture based on REST API
- Advantages and disadvantages

# Contact

- University of Stuttgart
- Universitaetsstr. 38, 70569 Stuttgart, Germany
- Felix Baumann, baumann@informatik.uni-stuttgart.de
- Q & A**